

AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

- 1-3. (Canceled)
4. (Currently Amended) A driving method of a PDP, comprising:
 - detecting each false contour generation regions from first video data for a previous frame period and second video data for a current frame period;
 - extracting a motion information from the first video data and the second video data including the detected false contour generation regions; and
 - compensating a false contour by using the extracted motion information, wherein the compensating comprises:
 - setting a compensation value based on a velocity value from the motion information, and
 - adding or subtracting the compensation value to or from a gray scale that has generated the false contour depending on a direction from the motion information, and
 - setting the compensation value based on a size of the gray scale, wherein the gray scale to or from which the compensation value is added or subtracted is any one of adjacent gray scales that generate a false contour generation region.

5. (Previously Presented) The method according to claim 4, wherein the first video data of the previous frame period is stored such that the first video data is delayed during one frame period by a frame memory.

6-8. (Canceled)

9. (Previously Presented) The method according to claim 4, wherein the false contour is generated when a gray scale having a combination of a plurality of sub-fields is any one of 16, 32, 64 and 128.

10. (Currently Amended) The method according to claim 4, wherein the extracting comprises:

matching the first video data of the previous frame period with the second video data of the current frame period; and

extracting the motion information from a change of the movement between first false contour generation region of the first video data and second false contour generation region of the second video data.

11. (Previously Presented) The method according to claim 4, wherein the motion information comprises size, direction and velocity value of a gray scale.

12-27. (Canceled)

28. (Currently Amended) A plasma display driving method, comprising:

determining false contour generation regions from first video data for a previous frame period and second video data for a current frame period;

determining motion information from the first video data and the second video data including the determined false contour generation regions; and

compensating a false contour by adjusting a gray scale based on the determined motion information, wherein the compensating includes:

adding or subtracting a compensation value to or from the gray scale depending on a direction of the motion information,

setting the compensating value based on a velocity value of the motion information, and

setting the compensation value based on a size of the gray scale, wherein the gray scale to or from which the compensation value is added or subtracted is any one of adjacent gray scales that generate a false contour generation region.

29-30. (Canceled)

31. (Previously Presented) The method according to claim 28, wherein the first video data of the previous frame period is stored such that the first video data is delayed during one frame period by a frame memory.

32. (Previously Presented) The method according to claim 28, wherein the false contour is generated when a gray scale having a combination of a plurality of sub-fields is any one of 16, 32, 64 and 128.

33. (Previously Presented) The method according to claim 28, wherein determining the motion information includes:

matching the first video data of the previous frame period with the second video data of the current frame period; and

determining the motion information from a change of movement between a first false contour generation region of the first video data and a second false contour generation region of the second video data.

34. (Previously Presented) The method according to claim 28, wherein the motion information includes size, direction and velocity value of a gray scale.

35. (Canceled)